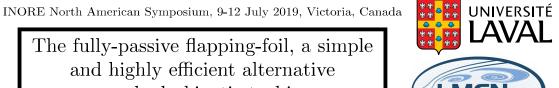




## The fully-passive flapping-foil, a simple and highly efficient alternative as a hydrokinetic turbine



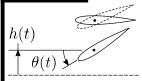


Québec 🕶 🕏

## Calcul Québec

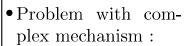
K. Gunther, M. Boudreau, G. Dumas Department of Mechanical Engineering, Laval University, Quebec City (Qc), Canada e-mail: kevin.gunther.1@ulaval.ca

## Context



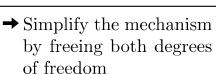
• When the heaving and pitching motions are constrained:

→ High energy extraction efficiency demonstrated numerically and experimentally



→ Loss of energy & reliability







Completely constrained experimental prototype Kinsey et al., RE (2010)

## $\theta(t)$ : pitch motion phase lag

Fully-passive concept

h(t): heave motion

Dynamic equations governing the motion of the foil

Heaving:  $F_y = m_h \ddot{h} + D_h \dot{h} + k_h h + (m_\theta x_\theta) (\ddot{\theta} \cos(\theta) + (\dot{\theta})^2 \sin(\theta))$ 

 $M = I_{\theta}\ddot{\theta} + D_{\theta}\dot{\theta} + k_{\theta}\theta + (m_{\theta}x_{\theta})\ddot{h}\cos(\theta)$ Pitching:

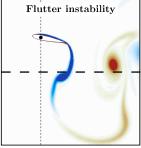
Idealized model

What has been done so far?

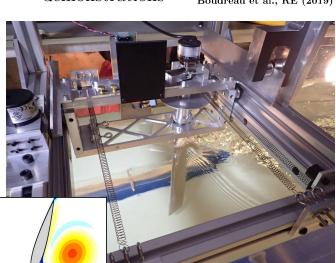
- 2D simulations with clean inflow conditions
- Experimental demonstrations

Divergence instability

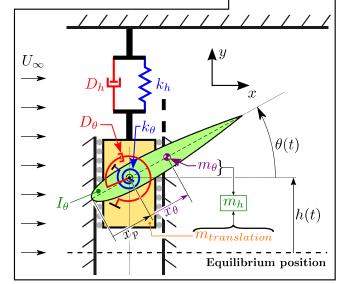
 $n_{max} = 33.6\%$  and



 $\eta_{max} = 51.0\%$  and no LEV Boudreau et al., RE (2019)



 $(\eta_{max}=31.0\%)$  - Experimental setup of the fully passive hydrokinetic turbine in a channel at the University of Victoria Boudreau et al., JFS (2018)



My M.Sc. project

What is next to investigate? Validate the concept by including:

- 3D effects
- Confinement effects
- Perturbed inflow conditions (shear flow, turbulence)